

# Network Theory 1

## Analoge Netzwerke

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Network Theory 1

S. 1

Fachgebiet  
Nachrichtentechnische Systeme



## Chapter 3

# Realization of active RC two-port networks



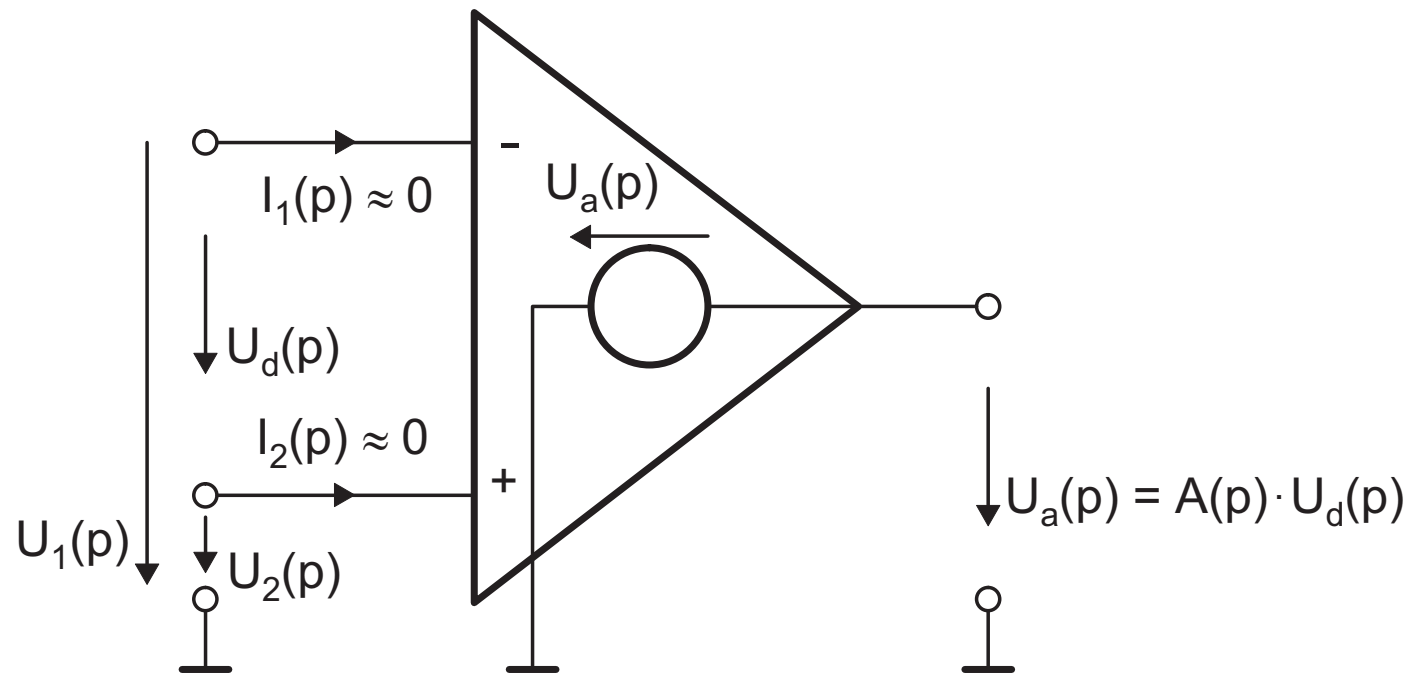
# 3.1 Preface

- The active RC two-port led to important developments and/or realization of high-performance operational amplifiers in integrated technology
- Here are some main reasons of this important development:
  - 1- Active RC two-port realize system functions with practically arbitrary pole zero configuration in avoidance of coils.
  - 2- OHM's resistances and special passive capacities as well as the necessary amplifiers can be produced very accurately in integrated technology and thereby fulfilling the conditions for miniaturized complex systems.
  - 3- The negative impedance converter and gyrator realizable with OHM's resistances and operational amplifiers extend the possibilities of realizing system functions.



## 3.2 The operational amplifier

A simple linear model for the description of the most important characteristics of real operational amplifiers looks like this symbol:



## 3.2 The operational amplifier

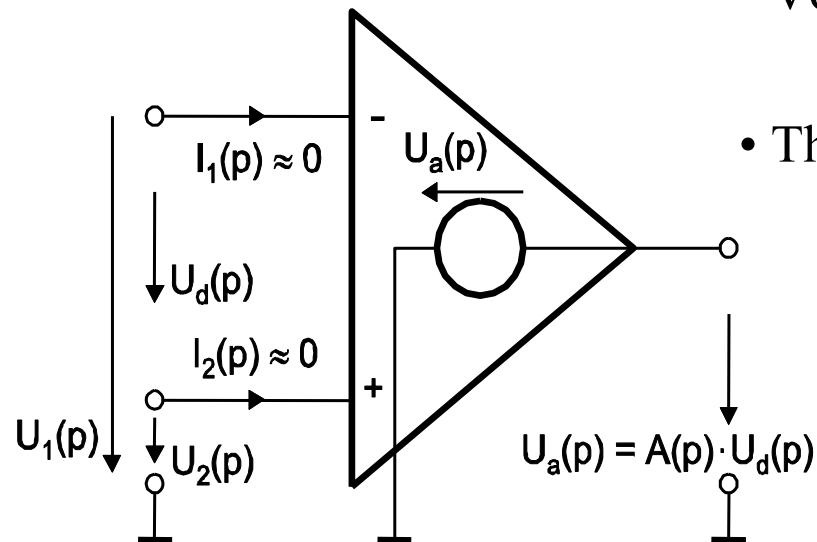
The model represents an idealization of the operational amplifier (op-amp) because:

- The internal amplifier DC-offset source and noise sources are neglected
- The internal resistance  $R_i$  of the internal voltage-controlled voltage supply is considered as 0 (usually from  $0.01\Omega$  ..  $5\Omega$ )
- The difference impedance  $Z_d$  is set to  $\infty$  (usually  $Z_d = 100k\Omega - 10M\Omega$ )
- The common mode input impedance  $Z_G(p)$  (usually  $2,5M\Omega - 10G\Omega$ ), which lies between  $E_1, E_2$  and the ground, is set also to  $\infty$ . Thus, there is no current flowing into  $E_1, E_2$  when  $Z_d$  is set to infinity.
- Any nonlinear  $u_a - u_d$  characteristic of the op-amp is neglected.



## 3.2 The operational amplifier

Under these conditions, one obtains the followings results:



- Voltage difference:  $U_d(p) = U_1(p) - U_2(p)$

- The output voltage:

$$U_a(p) = A(p) U_d(p)$$

- The open-loop amplification  $A(p)$ :

$$A(p) = \frac{A_0 \cdot \omega_g}{p + \omega_g} \text{ where } A_0 > 0$$

**Simple linear model of a  
real operational amplifier**

## 3.2 The operational amplifier

### Some discussions:

- The DC voltage open-loop gain  $A_0$  has the value  $10^3 \dots 10^7$
- The 3dB cut-off frequency  $\omega_g$  has values 1Hz ... 2kHz
- The transit frequency  $f_T$  is in the range 1 Mhz ... 200 MHz
- The operational amplifier output voltage is finite
- The open-loop voltage gain  $A_0 \gg 1$  leads to negligible differential input voltage (due to the large value of the output)
- Under normal operating conditions, practically one can consider with

$$U_1(p) \approx U_2(p) \text{ for } A_0 \gg 1$$

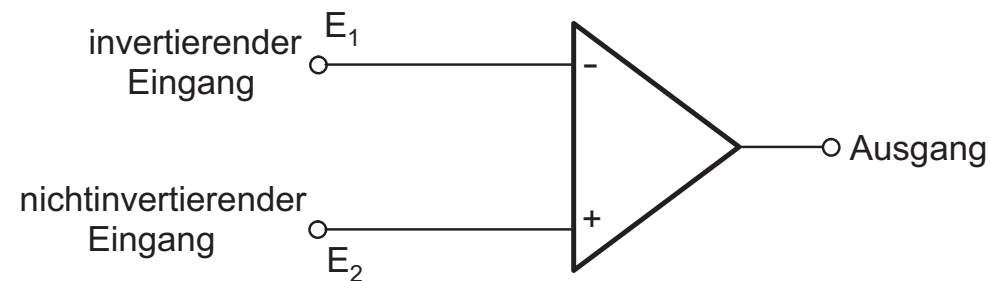
(due to feedback and large open-loop gain)



## 3.2 The operational amplifier

Using the linear operation amplifier model shown and  $A_0 \rightarrow \infty$ , the model of the **ideal operation amplifier is obtained** with the following characterizing relations:

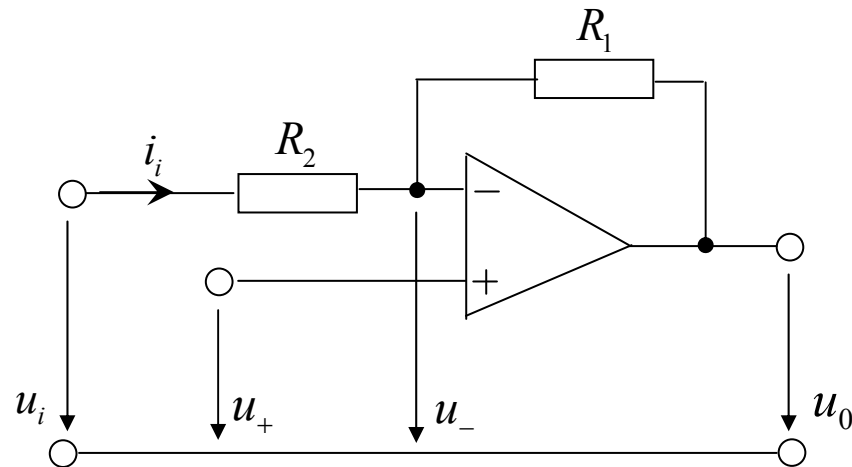
- $U_1(p) = U_2(p)$  for  $A_0 \rightarrow \infty$  where the output voltage exhibits finite values and is offset-free and noise-free.
- $I_1(p) = I_2(p) = 0$



### Symbol for an ideal operational amplifier



## 3.2 The operational amplifier



### Basic circuit of an operational amplifier

$$u_0 = A_0(u_+ - u_-)$$

$$u_i = i_i(R_1 + R_2) + u_0$$

$$u_- = u_i - i_i \cdot R_2$$

These relations can be solved for the output by eliminating  $u_-$  and  $i_i$ :

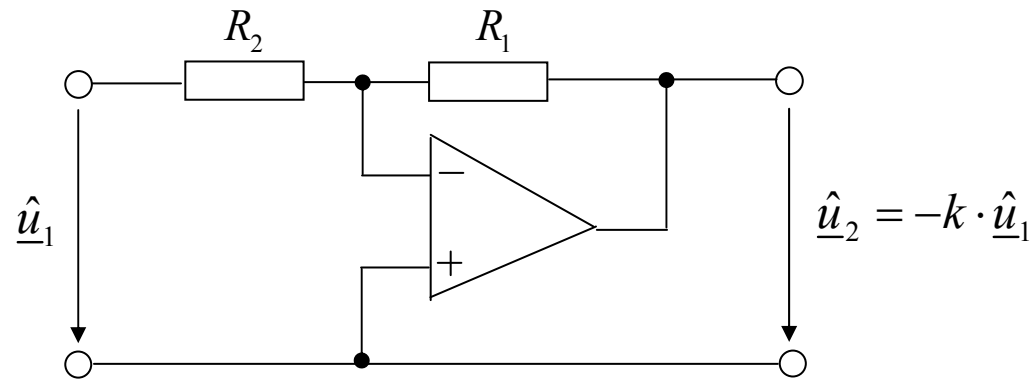
$$u_0 = \frac{u_+(1+k) - u_i k}{1 + (1+k)/A_0} \quad \text{with } k = \frac{R_1}{R_2}$$

Thus it results for  $A_0 \rightarrow \infty$ :

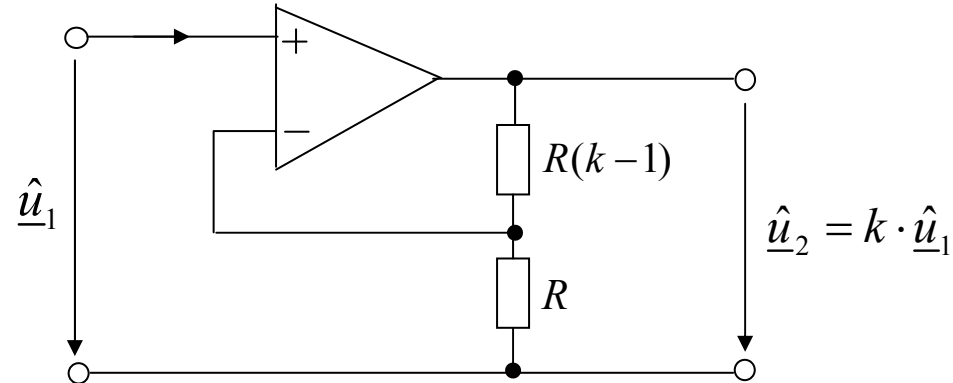
$$\begin{aligned} \lim_{A_0 \rightarrow \infty} u_0 &= u_+(1+k) - u_i k \\ &= k(u_+ - u_i) + u_+ \end{aligned}$$

# 3.2 The operational amplifier

First applications:



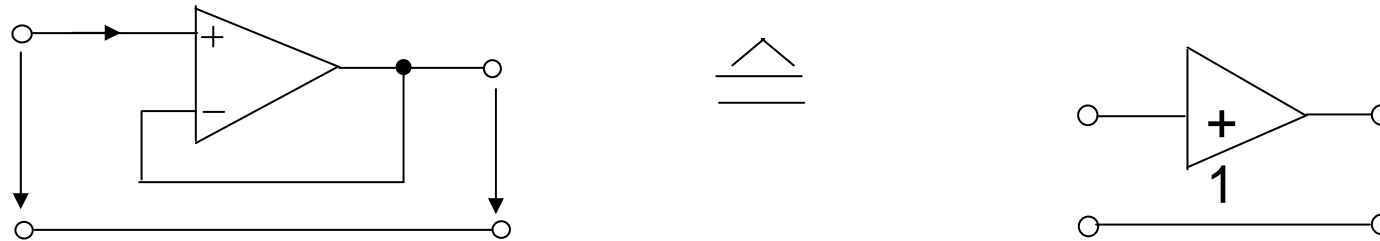
An amplifier with easily settable negative gain  $k$



An amplifier with easily settable positive gain

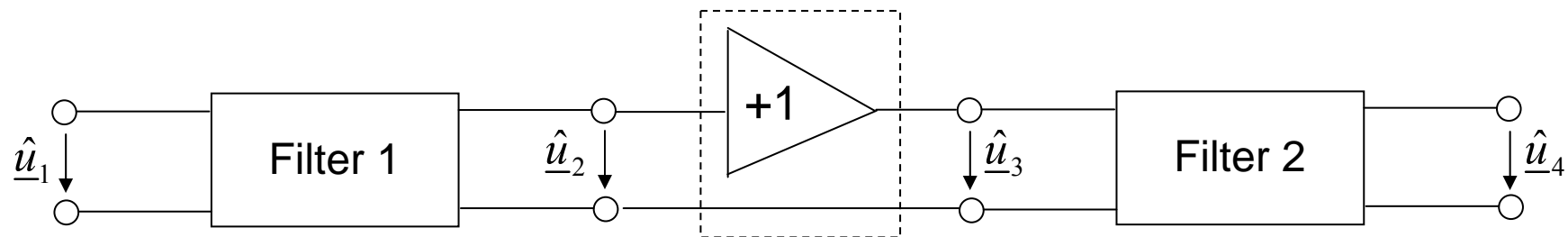
## 3.2 The operational amplifier

A special case but important case results for  $k = 1 \rightarrow R_1 = 0$  and  $i_- = 0$ :



Circuit of a voltage follower and its simplified symbol

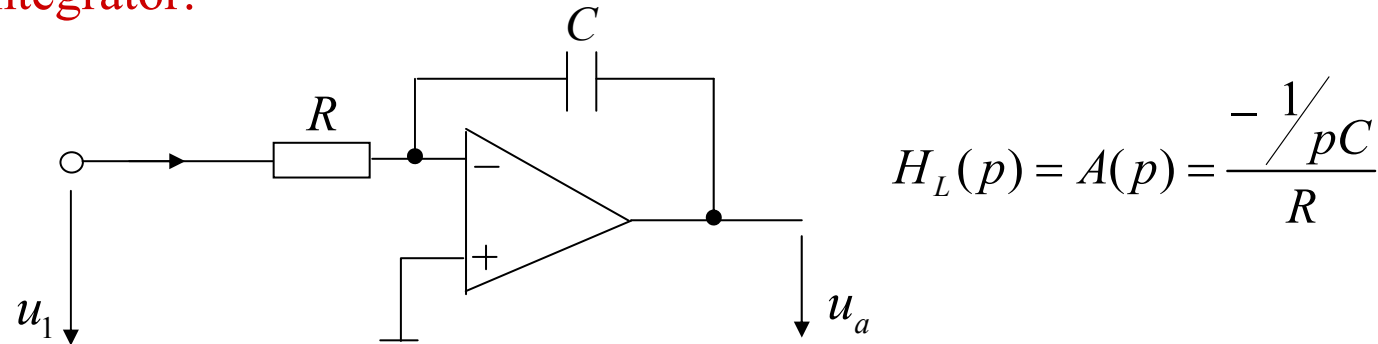
### Decoupling circuit



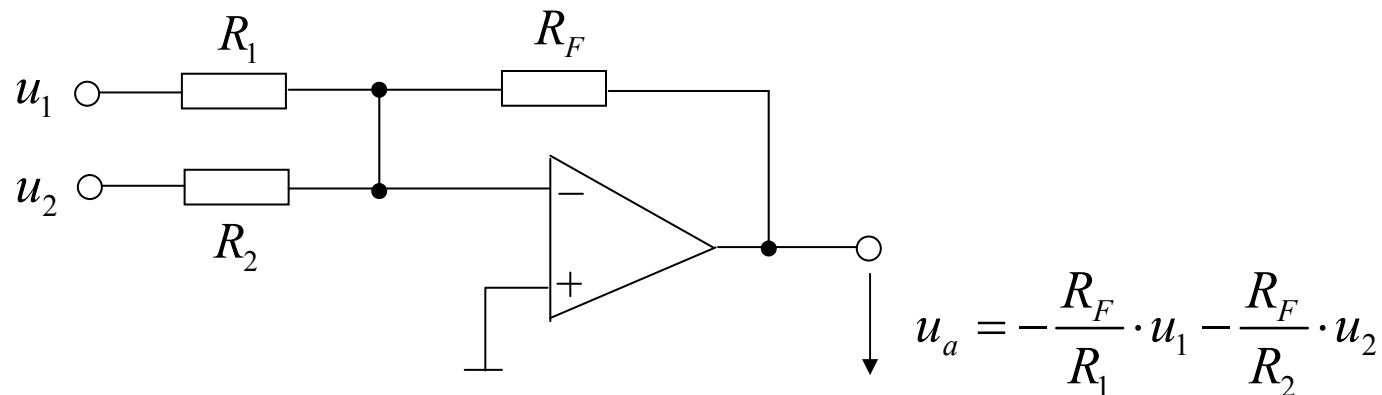
Use of a decoupling circuit in between filter modules

# 3.2 The operational amplifier

Ideal integrator:



Ideal adder:



## 3.3 Active RC two-port with infinitely amplifying Op-amp and individual feedback



# 3.3.1 Structure and Properties

Structure of an active RC two-port with ideal op-amp

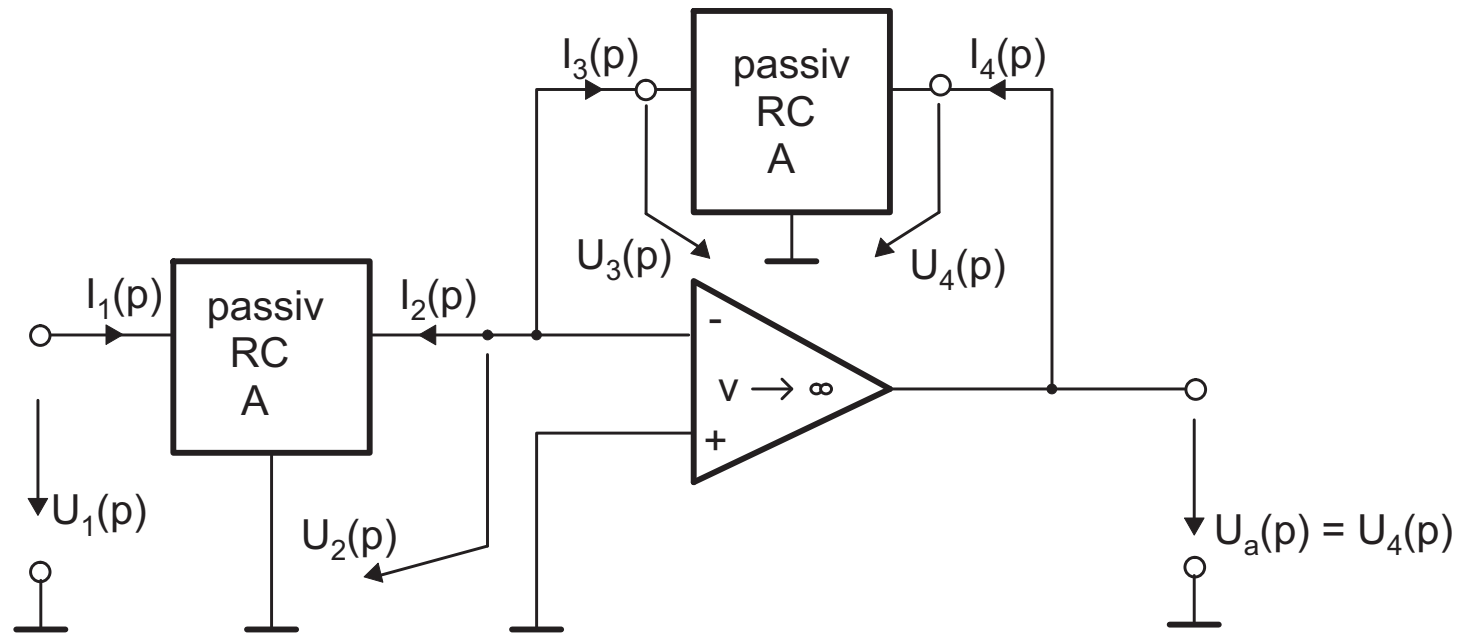


Fig. 3.3.1: Infinite gain single feedback circuit



## 3.3.1 Structure and Properties

It applies to the two-port A (being a normal passive two-port device):

$$I_1(p) = Y_{11A}(p) \cdot U_1(p) + Y_{12A}(p) \cdot U_2(p)$$

$$I_2(p) = Y_{21A}(p) \cdot U_1(p) + Y_{22A}(p) \cdot U_2(p)$$

Similarly for two-port B:

$$I_3(p) = Y_{11B}(p) \cdot U_3(p) + Y_{12B}(p) \cdot U_4(p)$$

$$I_4(p) = Y_{21B}(p) \cdot U_3(p) + Y_{22B}(p) \cdot U_4(p)$$



## 3.3.1 Structure and Properties

As shown in figure 3.3.1, one observes the following:

$$U_2(p) = U_3(p) = 0 \quad (\text{because input of opamp is virtually grounded})$$

under this condition, one gets:

$$I_2(p) = Y_{21A}(p) \cdot U_1(p)$$

and 
$$I_3(p) = Y_{12B}(p) \cdot U_4(p)$$

Furthermore, it is directly clear from figure 3.3.1 that:  $I_2(p) = -I_3(p)$

This gives:

$$Y_{21A}(p) \cdot U_1(p) = -Y_{12B}(p) \cdot U_4(p)$$

**System function of the network**

↓

$$\Leftrightarrow U_4(p) = -\frac{Y_{21A}(p)}{Y_{12B}(p)} \cdot U_1(p) = H_L(p) \cdot U_1(p) \quad \text{where} \quad H_L(p) = -\frac{Y_{21A}(p)}{Y_{12B}(p)}$$





## 3.3.1 Structure and Properties

The input admittance of the network can be determined as:

$$Y_e(p) = \left. \frac{I_1(p)}{U_1(p)} \right|_{U_2(p)=0} = Y_{11A}(p)$$

Pole and zero determination:

If one expresses  $Y_{21A}(p)$  and  $Y_{12B}(p)$  in terms of fractions, then:

- Poles of  $H_L(p)$  correspond to poles of  $Y_{21A}(p)$  together with zeros of  $Y_{12B}(p)$
- Zeros of  $Y_{21A}(p)$  together with poles of  $Y_{12B}(p)$  correspond to zeros of  $H_L(p)$

→ From this, the realization of RC network A and B can be derived based on the system function using pole and zero specifications!



## 3.3.2 The active 2nd order RC low-pass

Typical application example:

A stable second order low-pass with negative amplification for DC has the system function of

$$H_L(p) = -\frac{H_0 \cdot \omega_g^2}{p^2 + b \cdot \omega_g p + d \cdot \omega_g^2} = -\frac{H_0}{p^2 / \omega_g^2 + b \cdot p / \omega_g + d}$$

with  $0 < b < 2$  in case of  $d = 1$

and  $H_0 = H_L(0)$  (DC voltage gain)

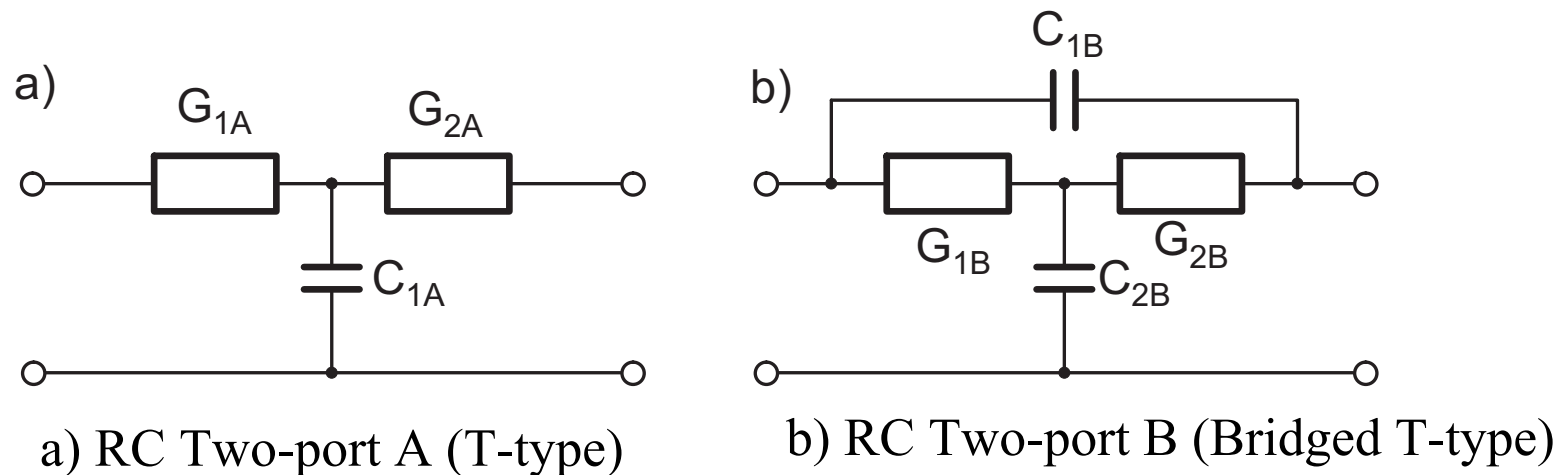
Under the conditions given above, the system exhibits accordingly the conjugated complex pair of poles for  $b < 2$  in case of  $d = 1$ :

$$p_{\infty 1,2} = -\frac{b}{2} \omega_g \pm j \omega_g \sqrt{1 - \frac{b^2}{4}}$$

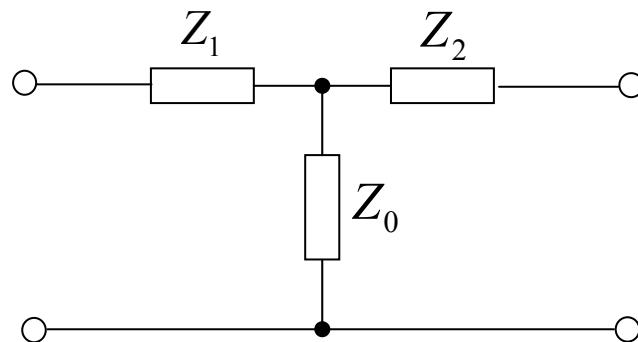


## 3.3.2 The active 2nd order RC low-pass

Passive RC two-ports for the realization of an active RC low-pass:



For any T-circuit like those shown above it holds:



$$\vec{Z} = \begin{pmatrix} Z_1 + Z_0 & Z_0 \\ Z_0 & Z_2 + Z_0 \end{pmatrix}$$

## 3.3.2 The active 2nd order RC low-pass

At first  $Y_{12}$  is determined using Z-parameters as follows:

$$Y_{12} = \frac{-Z_{12}}{\Delta Z} = \frac{-Z_0}{Z_1 Z_2 + Z_1 Z_0 + Z_0 Z_2} \quad \text{due to } \Delta Z = (Z_1 + Z_0)(Z_2 + Z_0) - (Z_0)^2$$

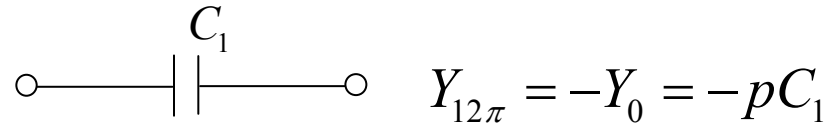
For the first part of two-port B (T-circuit without  $C_{1B}$  denoted by index „12T“) it holds:

$$\begin{aligned} Z_1 &= \frac{1}{G_{1B}} & Z_2 &= \frac{1}{G_{2B}} & Z_0 &= \frac{1}{pC_{2B}} \quad \Rightarrow \\ Y_{12T} &= -\frac{1}{pC_{2B}} \cdot \frac{1}{\frac{1}{G_{1B}G_{2B}} + \frac{1}{G_{1B}pC_{2B}} + \frac{1}{G_{2B}pC_{2B}}} \\ &= -\frac{1}{\frac{pC_{2B}}{G_{1B}G_{2B}} + \frac{1}{G_{1B}} + \frac{1}{G_{2B}}} = -\frac{G_{1B}G_{2B}}{pC_{2B} + G_{1B} + G_{2B}} \end{aligned}$$

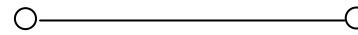


## 3.3.2 The active 2nd order RC low-pass

For the second part of two-port B ( $\pi$ -circuit), it holds:



Thus it results due to:



$$Y_{12B}(p) = Y_{12T} + Y_{12\pi}$$

$$\begin{aligned}
 Y_{12B}(p) &= -pC_{1B} - \frac{G_{1B}G_{2B}}{pC_{2B} + G_{1B} + G_{2B}} = -\frac{pC_{1B} \cdot (pC_{2B} + G_{1B} + G_{2B}) + G_{1B}G_{2B}}{pC_{2B} + G_{1B} + G_{2B}} \\
 &= -C_{1B} \frac{p^2C_{2B} + p \cdot (G_{1B} + G_{2B}) + G_{1B}G_{2B} / C_{1B}}{pC_{2B} + G_{1B} + G_{2B}} \\
 &= -C_{1B} \frac{p^2 + p \frac{G_{1B} + G_{2B}}{C_{2B}} + \frac{G_{1B}G_{2B}}{C_{1B}C_{2B}}}{p + \frac{G_{1B} + G_{2B}}{C_{2B}}}
 \end{aligned}$$



## 3.3.2 The active 2nd order RC low-pass

For the T-circuit of network A, which is similar to first part of network B, it holds:

$$Y_{21A}(p) = -\frac{G_{1A}G_{2A}}{pC_{1A} + G_{1A} + G_{2A}} = -\frac{\frac{G_{1A}G_{2A}}{C_{1A}}}{p + \frac{G_{1A} + G_{2A}}{C_{1A}}}$$

The system function of the filter then becomes:

$$H_L(p) = -\frac{Y_{21A}(p)}{Y_{12B}(p)} = -\frac{\frac{G_{1A}G_{2A}}{C_{1A}} \cdot \frac{1}{C_{1B}} \left( p + \frac{G_{1B} + G_{2B}}{C_{2B}} \right)}{\left( p + \frac{G_{1A} + G_{2A}}{C_{1A}} \right) \cdot \left( p^2 + \frac{G_{1B} + G_{2B}}{C_{2B}} p + \frac{G_{1B} \cdot G_{2B}}{C_{1B} \cdot C_{2B}} \right)}$$

A conjugate-complex pair of zeros in addition to a simple pole on the negative  $\sigma$ -axis can be realized by suitable choice of conductances  $G_{1B}, G_{2B}$  and capacities  $C_{1B}, C_{2B}$ .



## 3.3.2 The active 2nd order RC low-pass

The wanted system function in this example has no zero, so that the admittance function of RC two-port A must have an appropriated pole compensating the zero.

One pole and one zero of the system function can be cancelled from the fraction given above under the condition that:

$$\frac{G_{1A} + G_{2A}}{C_{1A}} = \frac{G_{1B} + G_{2B}}{C_{2B}} \quad (0)$$

Thus that the system function will be:

$$H_L(p) = -\frac{\frac{G_{1A} \cdot G_{2A}}{C_{1A} \cdot C_{1B}}}{p^2 + \frac{G_{1B} + G_{2B}}{C_{2B}} \cdot p + \frac{G_{1B} \cdot G_{2B}}{C_{1B} \cdot C_{2B}}}$$



## 3.3.2 The active 2nd order RC low-pass

Comparison of coefficients with the desired system function gives:

$$\frac{G_{1A} \cdot G_{2A}}{C_{1A} \cdot C_{1B}} = H_0 \cdot \omega_g^2 \quad \frac{G_{1B} + G_{2B}}{C_{2B}} = b \cdot \omega_g \quad \frac{G_{1B} \cdot G_{2B}}{C_{1B} \cdot C_{2B}} = \omega_g^2$$

These 3 relations together with the relation due to the zero compensation condition (0) is not enough to define all 7 unknown component values.

So another 3 additional relations/conditions are needed. Possibilities for such relations are e.g.:

$$C_{1A} = \frac{AG_w}{\omega_g} \quad (10) \quad C_{2B} = \frac{BG_w}{\omega_g} \quad (11) \quad G_{1B} = kG_w \quad (12)$$

with  $A, B, k$  and  $G_w$  set to suitable values.





## 3.3.2 The active 2nd order RC low-pass

With this 3 additional relations the previous 4 relations can be rewritten like this to solve the system of 7 equations:

$$(1) \quad \frac{G_{1A} \cdot G_{2A}}{AG_w \cdot C_{1B}} = H_0 \omega_g$$

$$(2) \quad \frac{kG_w + G_{2B}}{BG_w} = b \quad \Rightarrow \quad G_{2B} = BG_w b - kG_w = G_w (Bb - k)$$

$$(3) \quad \frac{kG_w G_{2B}}{C_{1B} BG_w} = \omega_g \quad \Rightarrow \quad C_{1B} = \frac{kG_w G_{2B}}{\omega_g BG_w}$$
$$= \frac{k}{\omega_g B} G_{2B} = \frac{G_w k}{\omega_g B} (Bb - k)$$

$$(4) \quad \omega_g \frac{G_{1A} + G_{2A}}{AG_w} = \frac{kG_w + G_{2B}}{BG_w} \omega_g \quad \Rightarrow \quad \frac{G_{1A} + G_{2A}}{A} = \frac{kG_w + G_{2B}}{B}$$



## 3.3.2 The active 2nd order RC low-pass

(1) gives with solved  $C_{1B}$  :

$$\frac{G_{1A} \cdot G_{2A}}{AG_w \cdot \frac{G_w k}{\omega_g B} (Bb - k)} = \frac{G_{1A} \cdot G_{2A} \cdot B\omega_g}{G_w^2 Ak(Bb - k)} = H_0 \omega_g \quad (5)$$

(4) gives with solved  $C_{1B}$  :

$$\frac{G_{1A} + G_{2A}}{A} = \frac{kG_w + G_w(Bb - k)}{B} = \frac{G_w Bb}{B} = G_w b$$
$$\Rightarrow G_{1A} + G_{2A} = AG_w b \quad \text{or} \quad G_{2A} = AG_w b - G_{1A} \quad (6)$$



## 3.3.2 The active 2nd order RC low-pass

(6) in (5) then gives:

$$\frac{G_{1A}(AG_w b - G_{1A})B}{G_w^2 Ak(Bb - k)} = H_0$$

$$\Rightarrow AG_w bB \cdot G_{1A} - B \cdot G_{1A}^2 = G_w^2 Ak(Bb - k)H_0$$

$$G_{1A}^2 - G_w Ab \cdot G_{1A} + G_w^2 Ak(b - k/B)H_0 = 0$$

$$\Rightarrow G_{1A_{1,2}} = G_w \frac{Ab}{2} \pm G_w \sqrt{\frac{A^2 b^2}{4} - Ak(b - k/B)H_0}$$

$$= G_w \frac{Ab}{2} \left( 1 \pm \sqrt{1 - \frac{4k(b - k/B)H_0}{Ab^2}} \right) = G_w \frac{Ab}{2} \left( 1 \pm \sqrt{1 - \frac{4k(bB - k)H_0}{ABb^2}} \right) \quad (7)$$

Parameters/sign must be chosen such that  $G_{1A}$  is positive and real!

$$\Rightarrow ABb^2 \leq 4k(bB - k)H_0$$



## 3.3.2 The active 2nd order RC low-pass

### An example of the design of an active RC low-pass

An active RC low-pass 2nd Order should show the following characteristics:

- DC voltage open-loop gain  $H_0 = 10$  ( $\hat{=} 20dB$ )
- Low-pass cut-off frequency  $f_g = 1 \text{ kHz}$
- Constants  $b = \sqrt{2}$  and  $d = 1$   
(these values are required for a BUTTERWORTH low-pass)

First, the following values are chosen arbitrarily:

- Constants  $k = 1$   $A = 2$   $B = 24$
- $R_w = 10 \text{ k}\Omega$



## 3.3.2 The active 2nd order RC low-pass

Then one obtains:

$$C_{1A} = 318 \text{ nF from (10)}$$

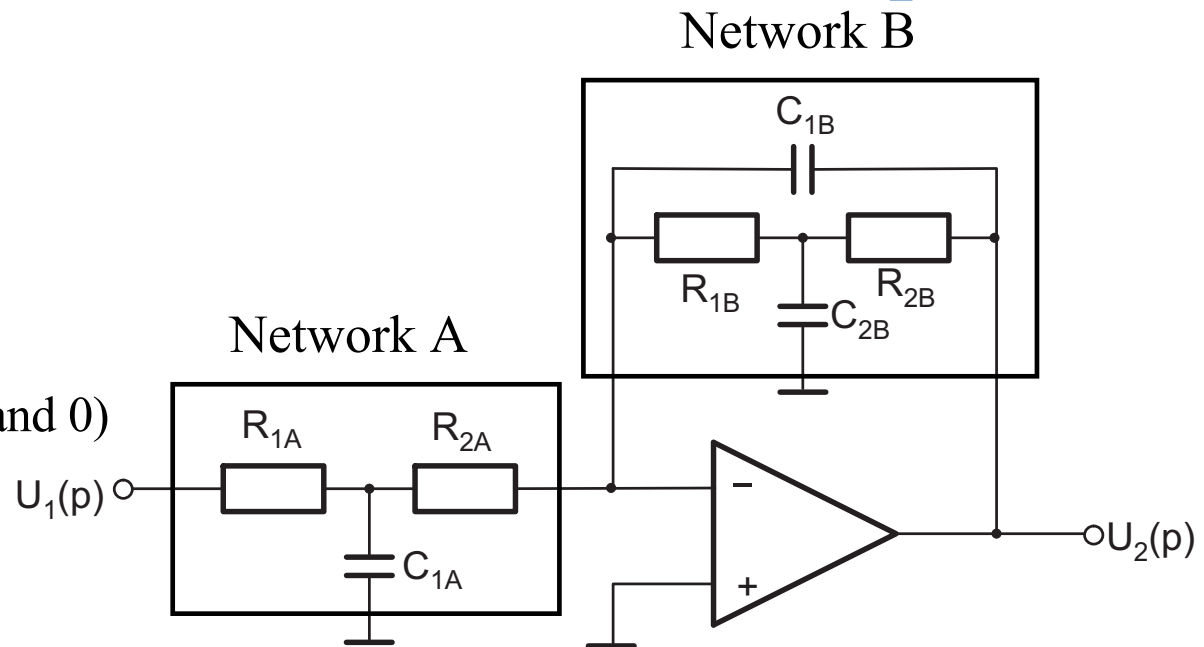
$$C_{2B} = 38,4 \text{ nF from (11)}$$

$$R_{1B} = 10 \text{ k}\Omega \text{ from (12)}$$

$$R_{1A} = R_{2A} = 707 \text{ }\Omega \text{ from (7 and 0)}$$

$$R_{2B} = 4,142 \text{ k}\Omega \text{ from (2)}$$

$$C_{1B} = 15,9 \text{ nF from (3)}$$



### Active RC low-pass 2nd Order (BUTTERWORTH)

Another, easier method is to directly specify all 3 capacitor values and then solve the equations given in S. 24.

For low-passes of 2nd order specialized circuits are known which simplify the design process even more.

## 3.3.3 The active 2nd order RC high-pass

The general stable second order high-pass with negative amplification for highest frequencies has the system function:

$$H_L(p) = -\frac{H_0 \cdot p^2}{p^2 + b \cdot \omega_g \cdot p + d \cdot \omega_g^2} \quad \text{with } \omega_g > 0, H_0 > 0, \text{ real and } 0 < b < 2$$

for  $d = 1$  and  $H_0 = \lim_{\omega \rightarrow \infty} \{-H_L(j\omega)\}$

The constant  $H_0$  gives the negative amplification for highest frequencies.

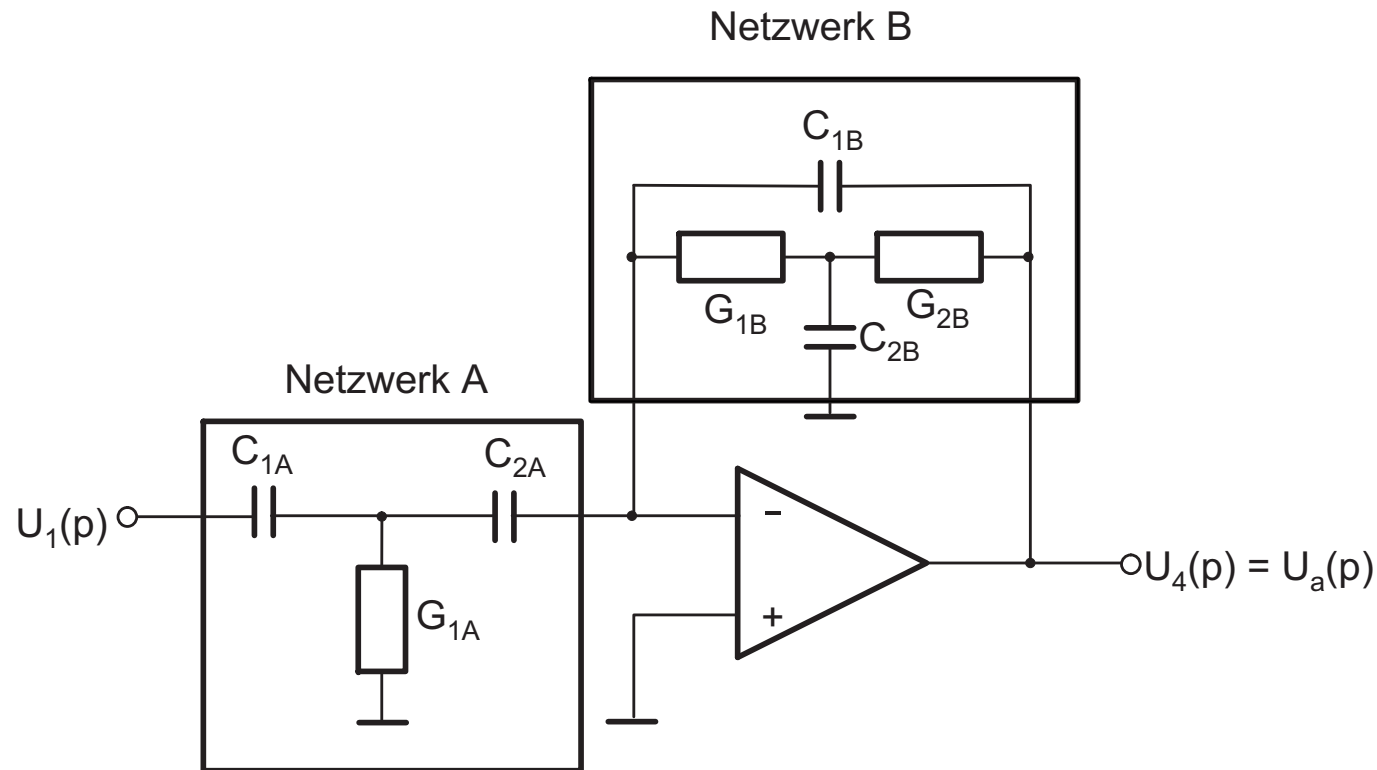
The constant  $b$  determines the behaviour around the cut-off frequency according to:

$$|H_L(j\omega_g)| = \frac{H_0}{b}$$

The realization of the system function using an ideal op-amp is illustrated in the following figure.



## 3.3.3 The active 2nd order RC high-pass



### Active 2nd order RC high-pass with an operational amplifier

## 3.3.3 The active 2nd order RC high-pass

Just like the active RC low-pass for the system function of the high-pass shown in the figure also applies :

$$H_L(p) = -\frac{Y_{21A}(p)}{Y_{12B}(p)}$$

The admittance function of network B is the same as for the second order RC low-pass, so it holds (see S.21):

$$Y_{12B}(p) = -C_{1B} \cdot \frac{p^2 + \frac{G_{1B} + G_{2B}}{C_{2B}} \cdot p + \frac{G_{1B} \cdot G_{2B}}{C_{1B} \cdot C_{2B}}}{p + \frac{G_{1B} + G_{2B}}{C_{2B}}}$$

For the high-pass and network A it follows (with respect to the T-circuit of S. 19 and 20):

$$Z_1 = \frac{1}{pC_{1A}} \quad Z_2 = \frac{1}{pC_{2A}} \quad Z_0 = \frac{1}{G_{1A}}$$





### 3.3.3 The active 2nd order RC high-pass

$$\begin{aligned} Y_{21A}(p) &= \frac{-Z_0}{Z_1 Z_2 + Z_1 Z_0 + Z_0 Z_2} \\ &= -\frac{1}{G_{1A} \left( \frac{1}{p^2 C_{1A} C_{2A}} + \frac{1}{p C_{1A} G_{1A}} + \frac{1}{p C_{2A} G_{1A}} \right)} = -\frac{p^2 C_{1A} C_{2A}}{G_{1A} \left( 1 + p \frac{C_{2A}}{G_{1A}} + p \frac{C_{1A}}{G_{1A}} \right)} \\ &= -\frac{p^2 C_{1A} C_{2A}}{G_{1A} + p(C_{1A} + C_{2A})} \\ &= -\frac{\frac{C_{1A} C_{2A}}{C_{1A} + C_{2A}} p^2}{p + \frac{G_{1A}}{C_{1A} + C_{2A}}} \end{aligned}$$



## 3.3.3 The active 2nd order RC high-pass

Therefore one obtains for the system function of the active RC high-pass:

$$H_L(p) = -\frac{Y_{21A}(p)}{Y_{12B}(p)} = -\frac{\frac{C_{1A}C_{2A}}{C_{1B} \cdot (C_{1A} + C_{2A})} \cdot p^2 \cdot \left( p + \frac{G_{1B} + G_{2B}}{C_{2B}} \right)}{\left( p^2 + \frac{G_{1B} + G_{2B}}{C_{2B}} \cdot p + \frac{G_{1B} \cdot G_{2B}}{C_{1B} \cdot C_{2B}} \right) \cdot \left( p + \frac{G_{1A}}{C_{1A} + C_{2A}} \right)}$$

Similarly as for the low-pass design the simple zero arising in this system function is waived under the following condition:

$$\frac{G_{1B} + G_{2B}}{C_{2B}} = \frac{G_{1A}}{C_{1A} + C_{2A}}$$



## 3.3.3 The active 2nd order RC high-pass

Under this condition, the system function becomes:

$$H_L(p) = -\frac{\frac{C_{1A}C_{2A}}{C_{1B} \cdot (C_{1A} + C_{2A})} \cdot p^2}{p^2 + \frac{G_{1B} + G_{2B}}{C_{2B}} \cdot p + \frac{G_{1B} \cdot G_{2B}}{C_{1B} \cdot C_{2B}}}$$

A comparison of coefficients gives for  $d = 1$ :

$$\frac{C_{1A}C_{2A}}{C_{1B} \cdot (C_{1A} + C_{2A})} = H_0 \qquad \frac{G_{1B} + G_{2B}}{C_{2B}} = b \cdot \omega_g$$

$$\frac{G_{1B} \cdot G_{2B}}{C_{1B} \cdot C_{2B}} = \omega_g^2$$



## 3.3.3 The active 2nd order RC high-pass

One can set for example three further conditional equations:

$$C_{1A} = C_{2A} \quad G_{1B} = \frac{1}{R_{1B}} = k \cdot G_W \quad C_{1B} = \frac{1}{\omega_g \cdot R_W} = \frac{G_W}{\omega_g}$$

With these 3 additional relations the previous 4 relations can be rewritten like this:

$$(1) \quad \frac{C_{1A} \cdot C_{2A}}{C_{1B} (C_{1A} + C_{2A})} = H_0 \Rightarrow \omega_g \frac{C_{1A}}{2G_W} = H_0 \quad (1a)$$

$$(2) \quad \frac{G_{1B} + G_{2B}}{C_{2B}} = b\omega_g \Rightarrow \frac{kG_W + G_{2B}}{C_{2B}} = b\omega_g \quad (2a)$$

$$(3) \quad \frac{G_{1B} G_{2B}}{C_{1B} C_{2B}} = \omega_g^2 \Rightarrow \frac{kG_W G_{2B}}{G_W C_{2B}} = \omega_g = \frac{kG_{2B}}{C_{2B}} \quad (3a)$$

$$(4) \quad \frac{G_{1B} + G_{2B}}{C_{2B}} = \frac{G_{1A}}{C_{1A} + C_{2A}} \Rightarrow \frac{kG_W + G_{2B}}{C_{2B}} = \frac{G_{1A}}{2C_{1A}} \quad (4a)$$



### 3.3.3 The active 2nd order RC high-pass

$$(1a) \Rightarrow C_{1A} = \frac{H_0 2G_w}{\omega_g}$$

(2a) inserted in (4a) gives:

$$b\omega_g = \frac{G_{1A}}{2C_{1A}} \Rightarrow G_{1A} = 2b\omega_g C_{1A} = 2b\omega_g \frac{H_0 2G_w}{\omega_g} = 4bH_0 G_w$$

(2) and (3) combined gives:

$$G_{1B} + G_{2B} = C_{2B} b\omega_g \Rightarrow C_{2B} = \frac{G_{1B} + G_{2B}}{b\omega_g}$$

$$G_{1B} \cdot G_{2B} = C_{1B} C_{2B} \omega_g^2$$



### 3.3.3 The active 2nd order RC high-pass

Inserting  $C_{2B}$  in the last equation gives:

$$G_{1B}G_{2B} = C_{1B} \frac{(G_{1B} + G_{2B})}{b\omega_g} \omega_g^2 = \frac{C_{1B}G_{1B} + C_{1B}G_{2B}}{b} \omega_g$$

$$\Rightarrow G_{2B} \left( G_{1B} - \frac{C_{1B}\omega_g}{b} \right) = \frac{C_{1B}G_{1B}\omega_g}{b}$$

$$\Rightarrow G_{2B} = \frac{C_{1B}G_{1B}\omega_g}{b \left( G_{1B} - C_{1B} \frac{\omega_g}{b} \right)} = \frac{C_{1B}G_{1B}\omega_g}{bG_{1B} - C_{1B}\omega_g} \left|_{G_{1B}=kG_w \text{ and } C_{1B}=\frac{G_w}{\omega_g}} \right.$$

$$= \frac{\frac{G_w}{\omega_g} G_w k \omega_g}{bG_w k - \frac{G_w}{\omega_g} \omega_g} = \frac{G_w k}{bk - 1}$$

with  $bk > 1$  to ensure positive admittance



## 3.3.4 The active RC band-pass 2. Order

The transmission characteristics of the general stable second order band-pass is described by the system function

$$H_L(p) = \frac{H_0 \cdot \omega_0 \cdot p}{p^2 + b \cdot \omega_0 \cdot p + \omega_0^2} \quad \text{with } \omega_0 > 0, H_0 > 0, \text{ real and } 0 < b < 2$$

with  $H_L(j\omega_0) = \frac{H_0}{b}$

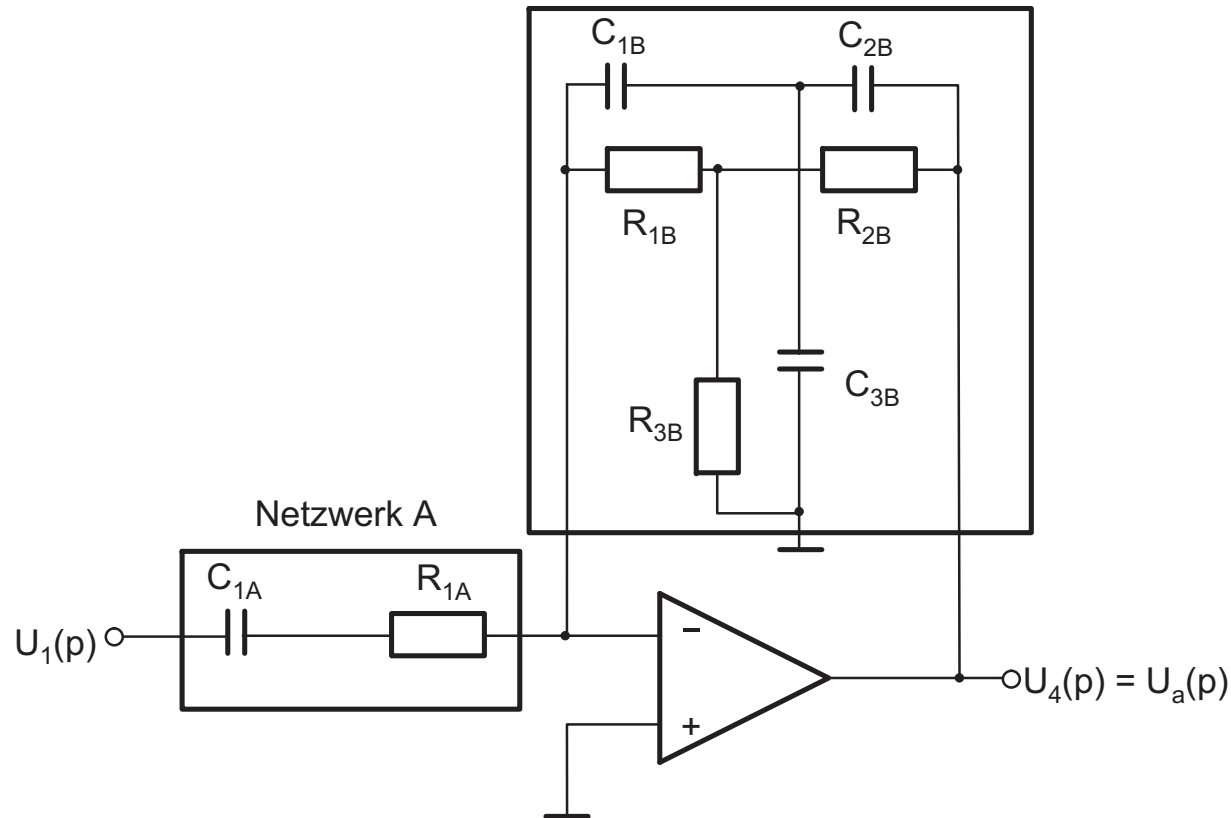
The realization of the system function according to the “Method of active RC two-port with ideal Op-amp and individual feedback path“ is illustrated in the following figure.



# 3.3.4 The active RC band-pass 2. Order

## Version 1

Netzwerk B



**Active 2nd order RC band-pass filter with an operational amplifier**



## 3.3.4 The active RC band-pass 2. Order

Network B now is separated into 2 T-circuits. For any T-circuit (see S. 19) it holds:

$$Y_{12T} = \frac{-Z_0}{\Delta Z}$$

Thus for the Resistor T-circuit with  $Z_0 = R_{3B}$   $Z_{1,2} = R_{1,2B}$  it holds:

$$\begin{aligned} Y_{12TR} &= \frac{-R_{3B}}{R_{1B}R_{2B} + R_{1B}R_{3B} + R_{3B}R_{2B}} = \frac{-1/G_{3B}}{\frac{1}{G_{1B}G_{2B}} + \frac{1}{G_{1B}G_{3B}} + \frac{1}{G_{2B}G_{3B}}} \\ &= \frac{-1}{\frac{G_{3B}}{G_{1B}G_{2B}} + \frac{1}{G_{1B}} + \frac{1}{G_{2B}}} = \frac{-G_{1B}G_{2B}}{G_{3B} + G_{2B} + G_{1B}} = \frac{-G_{1B}G_{2B}}{\sum G} \end{aligned}$$



## 3.3.4 The active RC band-pass 2. Order

Likewise for the capacitor-T-circuit it holds:

$$\begin{aligned} Y_{12TC} &= -\frac{p^2 C_{1B} C_{2B}}{p(C_{3B} + C_{2B} + C_{1B})} \\ &= -\frac{p C_{1B} C_{2B}}{C_{3B} + C_{2B} + C_{1B}} = -\frac{p C_{1B} C_{2B}}{\sum C} \end{aligned}$$

So finally for network B it holds:

$$\begin{aligned} \Rightarrow Y_{12B} = Y_{12TR} + Y_{12TC} &= -\frac{G_{1B} G_{2B}}{\sum G} - \frac{p C_{1B} C_{2B}}{\sum C} \\ &= -\frac{G_{1B} G_{2B} \sum C + p C_{1B} C_{2B} \sum G}{\sum G \cdot \sum C} = -\frac{p + \frac{G_{1B} G_{2B} \sum C}{C_{1B} C_{2B} \sum G}}{C_{1B} C_{2B}} \end{aligned}$$



## 3.3.4 The active RC band-pass 2. Order

Analysis of network A gives (see S. 21):

$$Y_{21A} = Y_{12A} = -Y_0 = -\frac{1}{R_{1A} + \frac{1}{pC_{1A}}} = -\frac{pC_{1A}}{pR_{1A}C_{1A} + 1} = -\frac{G_{1A}p}{p + G_{1A}/C_{1A}}$$

So finally we arrive with the resulting system function:

$$\begin{aligned} H_L(p) &= -\frac{Y_{21A}}{Y_{12B}} = \frac{G_{1A}p}{p + G_{1A}/C_{1A}} \cdot \frac{\frac{\Sigma C}{C_{1B}C_{2B}}}{p + \frac{G_{1B}G_{2B}\Sigma C}{C_{1B}C_{2B}\Sigma G}} \\ &= -\frac{G_{1A}\Sigma C}{C_{1B}C_{2B}} \cdot \frac{p}{p^2 + p\left(\frac{G_{1A}}{C_{1A}} + \frac{G_{1B}G_{2B}\Sigma C}{C_{1B}C_{2B}\Sigma G}\right) + \frac{G_{1A}G_{1B}C_{2B}\Sigma C}{C_{1A}C_{1B}C_{2B}\Sigma G}} \end{aligned}$$



## 3.3.4 The active RC band-pass 2. Order

A comparison with the desired system function

$$H_L(p) = \frac{H_0 \cdot \omega_0 \cdot p}{p^2 + b \cdot \omega_0 \cdot p + \omega_0^2}$$

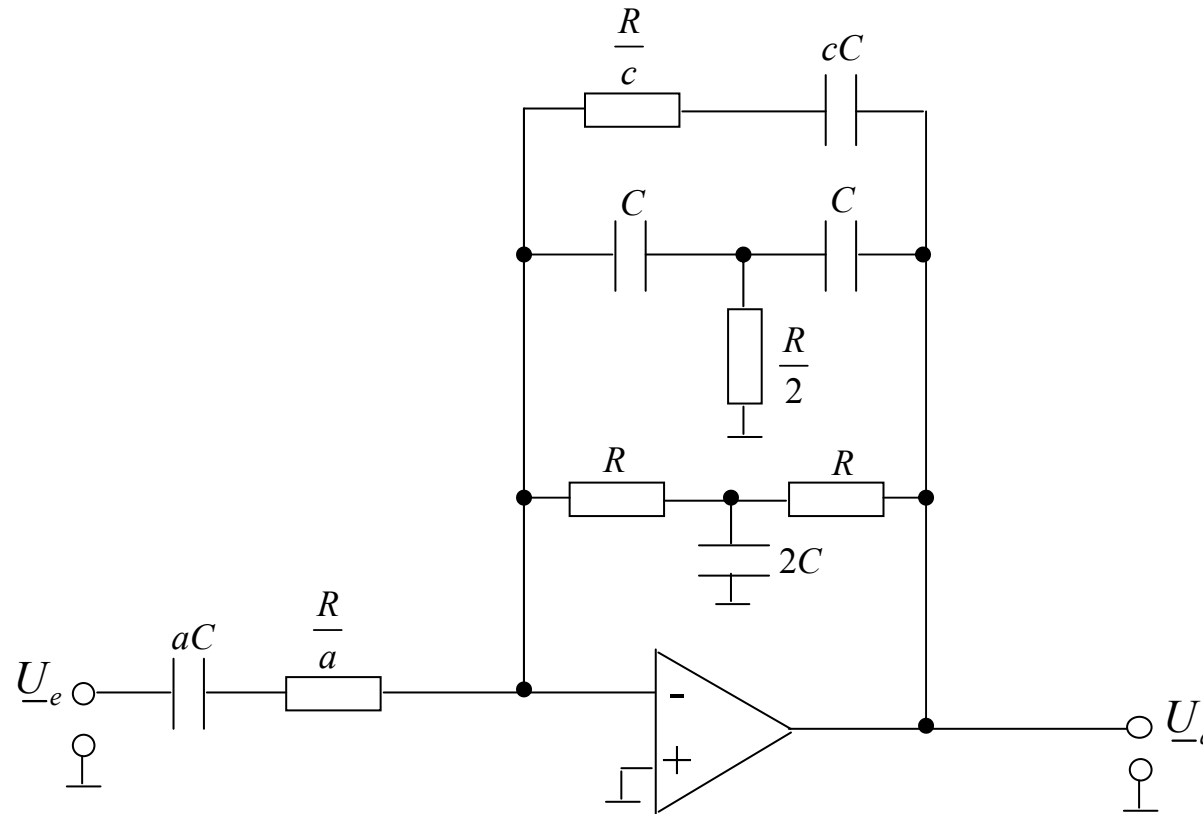
gives the following relations:

$$H_0 \omega_0 = \frac{G_{1A} \Sigma C}{C_{1B} C_{2B}} \quad b \omega_0 = \left( \frac{G_{1A}}{C_{1A}} + \frac{G_{1B} G_{2B} \Sigma C}{C_{1B} C_{2B} \Sigma G} \right) \quad \omega_0^2 = \frac{G_{1A} G_{1B} C_{2B} \Sigma C}{C_{1A} C_{1B} C_{2B} \Sigma G}$$

Another network with simplified calculation is shown in the next slides (according to “Tietze/Schenk, Halbleiter-Schaltungstechnik”):



## 3.3.4 The active RC band-pass 2. Order Version 2



Band-pass filter with simple feedback

## 3.3.4 The active RC band-pass 2. Order

Here we see the following relations (due to slides 43 and 22):

$$Y_{21A} = -\frac{1}{Z_0} = -\frac{1}{R/a + 1/(paC)} = -\frac{paC}{1 + paC \frac{R}{a}} = -\frac{paC}{1 + pRC}$$

$$Y_{12T} = \frac{-Z_0}{Z_1 Z_2 + Z_0(Z_1 + Z_2)}$$

is then evaluated for next 2 subcircuits:

$$Y_{12B \text{ Part1}} = -\frac{2pC}{R^2 + 2\left(\frac{R}{2pC}\right)} = -\frac{1}{2pR^2C + 2R} = -\frac{1}{2R(1 + pRC)} \quad (\text{Low-pass})$$

$$Y_{12B \text{ Part2}} = -\frac{R/2}{\frac{1}{p^2C^2} + \frac{R}{2} \frac{1}{pC}} = -\frac{p^2C^2R}{2(1 + pRC)} \quad (\text{High-pass})$$

$$Y_{12B \text{ Part3}} = -\frac{1}{Z_0} = -\frac{1}{\frac{R}{c} + \frac{1}{pcC}} = -\frac{pcC}{1 + \frac{R}{c} pcC} = -\frac{pcC}{1 + pRC} \quad (\text{according to } Y_{21A} \text{ result})$$



## 3.3.4 The active RC band-pass 2. Order

$$\begin{aligned}\Rightarrow Y_{12B} &= Y_{12Part1} + Y_{12Part2} + Y_{12Part3} \\ &= -\frac{1}{2R(1+pRC)} - \frac{p^2 C^2 R}{2(1+pRC)} - \frac{pcC}{1+pRC} \\ &= -\frac{1}{(1+pRC)} \left( \frac{1}{2R} + \frac{p^2 RC^2}{2} + pcC \right) \\ &= -\frac{1}{2R} \cdot \frac{1}{(1+pRC)} \cdot (1 + p^2 R^2 C^2 + 2pcRC)\end{aligned}$$



## 3.3.4 The active RC band-pass 2. Order

$$\begin{aligned}
 H_L(p) &= -\frac{Y_{21A}}{Y_{12B}} = -\frac{paC}{1+pRC} \frac{2R(1+pRC)}{1+2pcRC+p^2R^2C^2} \\
 &= -\frac{paC \cdot 2R}{1+2pcRC+p^2R^2C^2} \\
 &= -\frac{\frac{2a}{RC}p}{p^2 + p\frac{2c}{RC} + \frac{1}{R^2C^2}} \\
 &\stackrel{!}{=} -\frac{H_0\omega_0 p}{p^2 + b\omega_0 p + \omega_0^2} \quad \Rightarrow \quad \omega_0 = \frac{1}{RC}
 \end{aligned}$$

There are 4 unknowns ( $R, C, a, c$ ) and there are 3 conditional relations.

$\omega_0, H_0$  and  $b$  must be given.

So typically  $C$  is set to a convenient value to be able to solve the system of 3 equations.

$$b\omega_0 = \frac{2c}{RC} \Rightarrow c = \frac{\omega_0 b RC}{2} = \frac{b}{2}$$

$$H_0\omega_0 = \frac{2a}{RC} \Rightarrow a = H_0 / 2$$

